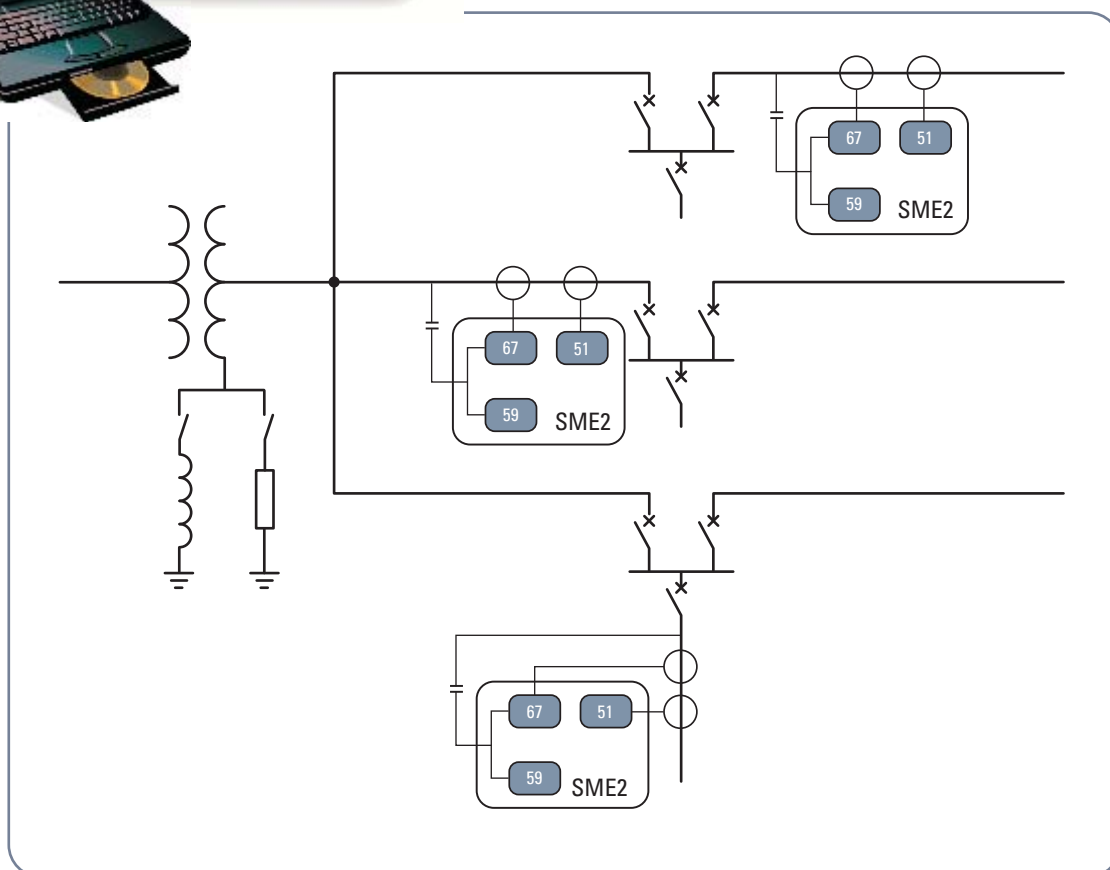


SME2

**DIRECTIONAL EARTH FAULT
AND SHORT-CIRCUIT DETECTOR**

MANUAL



General info

SME2 fault detection systems are designed in conformity with the ENEL DY 1059 (RGDAT) specification; they are installed in remote-controlled Secondary Stations in order to provide local and remote signalling of short circuit and earth faults that may occur in MV distribution networks. SME quickly locate the line section affected by the fault thus reducing power outage.

The SME2 device uses the signal provided by the capacitive voltage dividers fitted on MV panels both for the directional earth function and for the voltage failure detection function; the phase voltage values V4, V8 and V12 are processed so as to eliminate the capacitive divider measurement errors by means of a self calibration algorithm.

The current measure is taken by three open core current transformers supplied in the kit.

The SME2 device detects faults between phases producing a current exceeding the threshold and earth failures both on insulated neutral networks and on compensated neutral networks, without any need of changing the settings between different configurations and regardless of the feeding direction.

The device detects faults lasting more than 80 ms and is not sensitive to self-restoring faults lasting up to 40 ms.

The correct detection of the fault direction also occurs in the presence of intermittent faults.

The SME2 device checks the voltage of the three phases of the MT line and indicates whether it is ON or OFF; a current converter is also available with an impressed current output of 4...20 mA for sending the phase current measurement to the remote control terminal.

The device is provided with a self-calibration function capable of correcting errors and drifts (ageing or thermal) of capacitive transducers used to detect phase voltages.

The following output relays are provided:

- TS51A relay; it signals the short circuit function tripping for phase faults (between phases or double-phase to earth),
- TS67AV relay; it signals the directional earth function tripping in case of line faults (with reverse direction disabled),
- TSPRESV relay; it signals the dead line function tripping.

The following LEDs are provided:

- three green-coloured LEDs indicating the voltage presence on V4, V8, V12 phases,
- a white-coloured LED indicating the activation of the reverse direction for the directional earth protection,
- an orange-coloured latched LED indicating trip of the multiphase or double-phase to earth protection,
- a red-coloured latched LED indicating the trip of the earth fault protection ,
- a red-coloured LED indicating the calibration in progress,
- a red-coloured LED indicating the self test function (blinking).

A logical input allows enabling the reversal command for earth fault directional protection (67).

Protective functions

- 51 Phase overcurrent
- 67 Directional ground fault overcurrent
- 59 Voltage presence

2 MAIN FEATURES

SME panel

The SME2 panel is suitable for projecting assembly.
The front includes signalling LEDs and communication port.

Phase Current Sensor

Two open core ring type current transformers are designed so as to be mounted directly on the medium voltage insulated cables.

Residual current sensor

The IE> sensor is an open core ring type current transformer.
The sensor is installed on insulated cables so as the earth connection of the cable armour must pass through the transformer.
Since the core embeds the three line phases, the residual current is detected.

Current sensors connections

Current sensors connections are implemented through a harness conforming with the ENEL DY1059 specification; they must be connected to the MA terminal board located inside the SME2 panel.

Voltage sensors connection (Capacitive dividers)

Voltage sensors connection is implemented through screened cable between the fixed outlet on the MV panel and the SME2 device through hexapolar plug conforming with the ENEL DY811 specification.

Remote control unit

Remote control unit connections are implemented according with ENEL DY1059 specification; they are abutted to the terminal board MB at the factory according to the connection diagram into the device cover.

RS232 communication

The device provides a serial interface to allow a PC connection for installation, configuration, monitoring and diagnostic.

- The firmware upgrade is provided.
- To connect to the PC an adapter may be provided on request (SOC003 converter).

3 FUNCTION CHARACTERISTICS

The SME2 device performs its fault detection functions based on measure of line currents and phase voltages; two phase currents, three phase voltages and the residual current are detected.
The following features are provided.

Earth single-phase fault directional detection function

The function detects the occurrence of earth faults both on insulated neutral networks and on compensated neutral networks, without any need of changing settings when changing type of network. The algorithm is based on the numerical analysis of signals (FFT) through fast sampling (64 samples per period) and phase locking algorithm (PLL); in this way the quantities are correctly measured in Through external signal from the remote control system, it is possible to control the reversal of the reference direction in case of line feeding from the opposed side (secondary station bar tripping directionality); the reversal signal is provided by the remote control system through the closing of a contact connected to terminals 8 and 9 of the MB terminal board.

The fault signal (TS67AV) is provided to the remote control unit by the closing of a contact connected to terminal 5 of the MB terminal board.

The sensitivity of the earth directional function depends on the extension of the line and on the neutral status (insulated or with Petersen coil).

The setting is based on the adjusting of a U_0 residual voltage^[1] threshold adjustable in the 1...16% U_n range and a I_0 zero sequence current^[2] adjustable in the 1...9 A range.

The protective element detects the directional earth fault if all the following conditions occur:

- Residual voltage exceeds the U_0 > threshold ,
- Residual current exceeds the I_{ED} > threshold I_{ED} > ,
- Residual current - residual voltage displacement between 60 ° and 255 ° (I_{ED} lags behind to U_0 with reversed direction disabled),
- All the above conditions were met for almost 80 ms.

Note 1 - The residual voltage U_0 is the vector sum of the three phase voltages divided by three.

Note 2 - The residual current I_E is the vector sum of the three phase currents.

Double earth single-phase or phase-phase (short circuit) fault detection function

- The L4 and L12 phase currents are measured and fault indication is provided when current in at least one phase exceeds the set threshold a:
- 500 A for multi-phase faults
- 150 A for double earth-phase faults).

The fault signal (TS51A) is provided to the remote control unit by the closing of a contact connected to terminal 2 of the MB terminal board.

Voltage presence

The three phases voltages are measured; when at least one voltage value is higher than 80% of the rated voltage the information (TSV) is provided to the remote control unit by the closing of a contact connected to terminal 3 of the MB terminal board.

Current converter

The SME2 device is provided with an impressed current analogue output for sending the phase current measure to the remote control unit. Signal 4...20 mA is available for transfer to the remote control unit on terminals 4 (M1 connected to the positive auxiliary power) and 7 (M2 of terminal board MB). The rated primary current is adjustable inside the 100...500 A range with 100 A step.

Calibration

The calibration procedure aims to adjust the SME2 device voltage inputs to the capacitive dividers mounted on secondary switchgears; it should be carried out without faults on the network. The self calibration The phase voltages and acquired and the voltage parameters are normalized. The automatic calibration process is started with PC command. The computed parameters are stored to a nonvolatile memory and maintained when auxiliary power is goes down.

Output relay commissioning

The output relays TS51A and TS 67AV trip as for faults causing the switch to open, as for transient faults. Relays are energised for the fault time, and in any case for a minimum of 150 ms.

The following cases are covered:

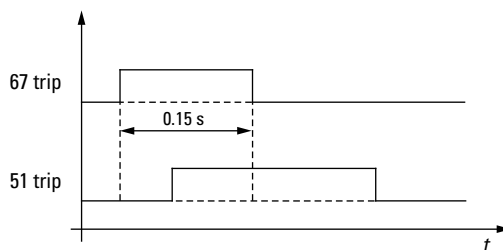
- single-phase ground fault with residual current $I_E \leq 150$ A: the directional protection trips (67) if the direction is correct,
- single-phase ground fault with current $I_E > 150$ A: the short circuit (51) protection trips,
- double single-phase earth fault with current $I_E \leq 150$ A (on the same line or on different lines): the 67 trips if the direction is correct,
- double single-phase earth fault with current exceeding 150 A (on the same line or on different lines): the 51 protection trips,
- multi-phase fault with residual current $I_E > 500$ A: the 51 protection trips.
- voltage presence indication: the TSV relay remains energised as long as the three phase voltages remain below the voltage off threshold (20% U_n).

The operation of directional earth fault protection (67) is masked by the trip of the phase overcurrent protection (51) according to the logic shown in Figure below.

Voltage presence

Two thresholds are provided:

- 80% of rated voltage for trip (4% accuracy),
- 20% of rated voltage for reset (4% accuracy).



Operating logic for masking the 67 trip implemented through the trip of the 51 protection

The transition between the states of presence / absence voltage is described:

- Starting from the no voltage condition (Voltage Presence OFF), the logic state of supply voltage is detected when, for at least 250 ms the following condition is true:

$(V4 > 80\%V_n) \text{ OR } (V8 > 80\%V_n) \text{ OR } (V12 > 80\%V_n)$

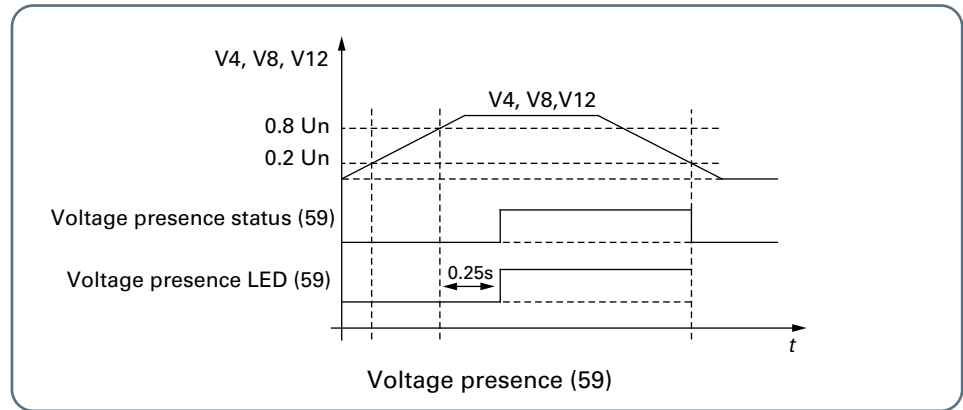
- Starting from the condition of Voltage Presence ON, the logic state is no longer recognized if the following condition is true:

$(V4 < 20\%V_n) \text{ AND } (V8 < 20\%V_n) \text{ AND } (V12 < 20\%V_n)$ without intentional delay.

- In case of fall and recovery of 24 V_{DC} power supply, the logic state starts no voltage condition (Voltage Presence OFF) and only if the following condition is true:

$(V4 > 80\%V_n) \text{ OR } (V8 > 80\%V_n) \text{ OR } (V12 > 80\%V_n)$ the voltage presence is recognized

The voltage presence logic is shown



Led indicators management

The SME2 device is provided with 8 indicator LEDs:

- three green LEDs indicating that V4, V8, V12 phase voltages are ON,
- a white LED indicating the direction reversal for the directional earth protection,
- an orange LED indicating the multiphase or double single-phase function tripping,
- a red LED indicating the earth fault function tripping downstream of the device,
- a green LED indicating the calibration in progress condition,
- a red LED indicating the self-test function tripping.

The fault indicator LEDs light up when a fault occurs which causes the opening of the switch, and they remain open until the three phase voltages return and remain for at least one second at a value of more than 80% the rated phase voltage.

The V4, V8, V12 LEDs, light up if the voltage of the relative phase is greater than 0.8 Vn and go OFF when the voltage is less than 0.2 Vn.

Glossary/definitions

50/51	Phase overcurrent ANSI code
59	Voltage presence ANSI code
67	Directional ground fault ANSI code
Vn	Rated voltage
In	Rated current (500A)
V4, V8, V12	Phase voltages
I>	Phase overcurrent threshold (51)
t>	Operate time (51)
IED>	Directional ground fault threshold (67)
U0>	Residual voltage threshold (67)
tED>	Operate time (67)
U>	Voltage presence threshold (59)

4 TECHNICAL DATA

4.1 GENERAL

□ Insulation

Reference standards	EN 60255-5 IEC 60255-5
High voltage test (50 Hz 60 s)	
• Auxiliary power supply	1 kV
• Input circuits	1 kV
• Output circuits	1 kV
• Output circuits (between open contacts)	1 kV
Impulse voltage withstand test (1.2/50 μ s):	
• Auxiliary power supply	2 kV
• Input circuits	2 kV
• Output circuits	2 kV
• Output circuits (between open contacts)	2 kV
Insulation resistance	>100 M Ω

□ EMC tests for interference immunity

Reference standards	
• Product standard for measuring relays	EN 50263
• Generic standards immunity for industrial environments	EN 61000-6-2
• Apparatı di automazione e controllo per centrali e stazioni elettriche (ENEL utility standard)	
- Compatibilit� elettromagnetica - Immunit�	ENEL REMC 02
- funzione del rivelatore di guasto	protezione
- ambiente di installazione	stazione MT
- porta di segnale	collegamenti locali

□ Climatic tests

Reference standards	IEC 60068-x ENEL R CLI 01 CEI 50
Ambient temperature	-10...+55 $^{\circ}$ C
Storage temperature	-40...+85 $^{\circ}$ C
Relative humidity	10...95 %
Atmospheric pressure	70...110 kPa

□ Mechanical tests

Reference standards	
- Normativa di compatibilit� elettromeccanica per apparati e sistemi (ENEL utility standard)	ENEL REMC 01

□ Reference standards

Rivelatore di guasto direzionale (RGDAT) (ENEL utility standard)	ENEL DY 859
Prescrizioni per la costruzione ed il collaudo	ENEL DY 1059 Ed.02-2004

□ Other applicable standards

• Electric relays	EN61810-1 (ex CEI 41-1) IEC 60255
• Protection degree (IP code)	EN60529, EN60529/A1
• EMC Directive	89/336/EEC
• Low Voltage Directive	73/23/EEC

□ Technical data

Mounting:	
• Phase current transformer	on isolated cable
• Residual current transformer	on isolated cable
• SME2 device	Projecting
Protection degree	IP31
SME2 mounting position	vertical
Mass:	
• Phase current transformer	0.3 kg
• Residual current transformer	0.7 kg
• SME2 device	0.9 kg

4.3 Input circuits

□ Auxiliary power supply U_{aux}

Rated voltage	24 V-
Nominal value (range)	19...29 V-
Max alternating component	10%
Maximum time at power ON	0.10 s
Power consumption at rest condition	2.5 W
Max power consumption	4 W

□ Phase current transformer

Inside diameter	50 mm
Rated current I_n	500 A
Permanent overload	4 I_n
Thermal overload (1 s)	100 I_n
Dynamic overload (10 ms)	250 I_n
Frequency:	
• Rated frequency f_n	50 Hz
• Operative range	0.95...1.05 f_n
Connection to SME2	
• type	unipolar wires
• section	1 mm ²
• length	3.5 m

□ Residual current transformer

Inside diameter	150 mm
Permanent overload	1 kA
Thermal overload (1 s)	12.5 kA
Dynamic overload (10 ms)	31.5 kA
Frequency:	
• Rated frequency f_n	50 Hz
• Operative range	0.95...1.05 f_n
Connection to SME2	
• type	unipolar wires
• section	1 mm ²
• length	3.5 m

□ Phase voltage input circuits

Voltage plug	DY811
MV rated voltage	15, 20, 23 kV
Transformation ratio	200...1800
Capacitive reactance (MTV side)	100...700 MΩ
Connection to SME2	
• type	shielded wires
• section	0.5 mm ²
• length	3.5 m

□ Binary input

Quantity	1
Type	optocoupler
Operative range	rated U_{aux}
Max consumption, energized	3 mA

4.4 Output circuits

□ Relays

Quantity	3
Type of contacts	make (SPST-NO, type A)
Nominal current	2 A
Nominal voltage	250 V
Breaking capacity (24 V, L/R = 40 ms)	0.2 A
Minimum switching load	300 mW (5 V/5 mA)

□ Current converter

Operating range	0...500 A
Output current	4...20 mA
Accuracy	10%
Max load	750 Ω
Maximum response time	300 ms

4.5 LEDs

□ Signalling LEDs

Voltage presence (V4)	green LED
Voltage presence (V8)	green LED
Voltage presence (V12)	green LED
Trip direction $I_{ED} > (INV\ 67)$	white LED
Trip $I > (51A)$	orange LED
Tripe $I_{ED} > (67AV)$	red LED
Calibration in progress (CALIBRATION)	red LED
Self test	red LED

□ Connection to the remote control unit

Type	9 wires multipolar cable
Section	1 mm ²
Length	8 m

4.6 COMMUNICATION INTERFACE

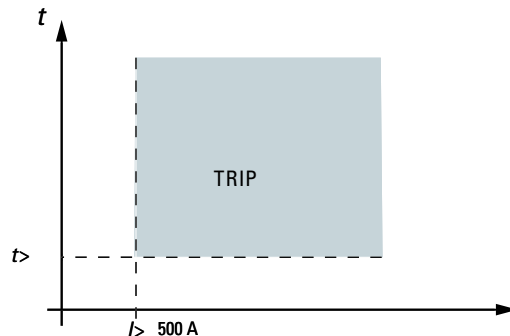
□ Local port

Connection	RJ45
• RS232-copper adapter	SOC003
Rate	9600 Bps
Parity	None
Protocol	ModBus RTU®

4.7 PROTECTION AND CONTROL FUNCTIONS

□ Overcurrent (51)

$I > \text{threshold}^{(1)}$	500 A
Operate time (definite time characteristic)	0.12 s
Dropout ratio	> 0.95
Reset delay	0.02 s
Duration of the fault not detected	0.04 s
Duration of the fault detected	0.08 s
Reference values	rest: 0
	trip: 1.2 $I >$
Threshold accuracy	$\pm 10\%$
Operate time accuracy	$\pm 3\% \pm 20 \text{ ms}$



General operation time characteristic for the phase overcurrent element - 50/51

Note 1: For multi-phase faults the operating threshold is 500 A, for single-phase or multi-phase double earth fault the operating threshold is 150 A

□ Voltage presence (59)

$U > \text{threshold}$	0.80 V_n (1)
Operate time (definite time characteristic)	0.25 s
Dropout ratio	0.25
Reset delay	0.04 s
Reference values	rest: 0
	trip: 1.0 V_n
Threshold accuracy	$\pm 4\%$
Operate time accuracy	$\pm 3\% \pm 20 \text{ ms}$

Note: The 59 protection trips when the value of at least one phase voltage is greater than 0.8 V_n and is reset when the voltage of all three phases is less than 0.2 V_n .

□ Directional earth fault overcurrent (67)

$I_{ED} > \text{threshold}^{(1)}$

$U_0 > \text{threshold}$

Operate $t_{ED} > (\text{definite time characteristic})$

Dropout ratio

Reset delay

Duration of the fault not detected

Duration of the fault detected

Reference values

Threshold accuracy

Operate time accuracy

Angular sector accuracy ($U_0=1...120\%$; $I_E=1...150\text{ A}$)

Hysteresis on the sector output

1.0...9.0 A (step 0.5 A)

0.01...0.16 V_n (step 0.01 V_n)

0.15 s

> 0.95

0.03 s

0.04 s

0.08 s

rest: 0 V, 0 A

trip: $2I_{ED}, 2U_0 >$

$\pm 15\%$

$\pm 3\% \pm 20\text{ ms}$

$\pm 2^\circ$

$\leq 3^\circ$

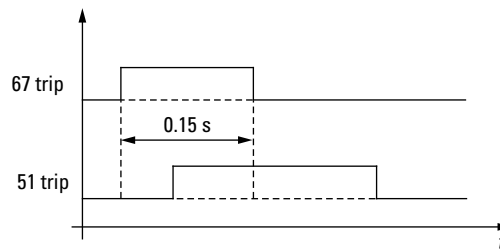


General operation time characteristic for the 67 element

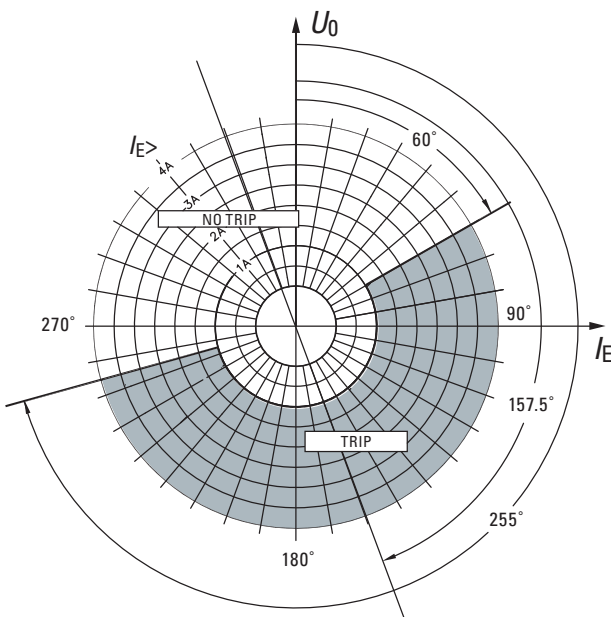
Note (1) The directional earth fault function operate whenever the set residual voltage threshold $U_0 >$ is exceeded with a residual current $I_E >$ higher than threshold with a defined phase relation.

The masking time as voltage is restored is 0.15 s.

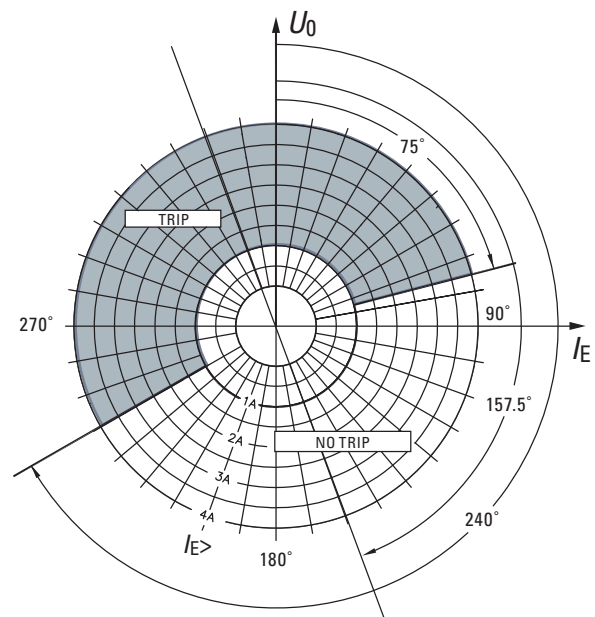
The operation of the directional earth fault protection is masked by the overcurrent trip according to the logic function described below:



Operating logic for masking trip of the 67 protection with trip of the 51 protection



Polar tripping characteristic (67) with reversing direction OFF



Polar tripping characteristic (67) with reversing direction ON

5 INSTALLATION

SME2 device

For fixing you must:

- remove the cover by unscrewing the fastening screws;
- fix the SME panel fitting the four M5 screws supplied into the holes on the case bottom; the operation is made easier by the presence of the slotted holes.

Current sensors

Since current shorting connectors are not provided for the secondary CT's, the current sensors must be installed at the same time with the SME device and connected at once. In case of replacing and/or maintenance operation of amperometric circuits, it is indispensable that the circuit breaker is OFF.

Since the earth fault detection function is directional, the toroid fitting direction must be complied with, or the device could fail to operate.

The assembly of the current sensors must be performed in the same way for feeders or incoming lines (operation according to the output direction from the switchgear).

Phase current sensors

For fixing you must:

- split the two core parts removing the metal clamp fastening screw;
- fit the core to the phase conductor by properly coupling the two parts forming the sensor and make attention that the earth connection of the cable shield don't pass through the sensor. The two phase current sensors supplied into each package have a different colour with respect to the container for an easier coupling; in particular, the two half-cores should be aligned properly so that references "P1" on the same cores are matching. For mechanical stability reasons, the sensor fitting direction should be such as to have said references arranged towards the upper side of the MT switchgear.
- apply the metal clamp and tighten the fastening screw;
- anchor the core to the phase conductor using the insulating clamps supplied.

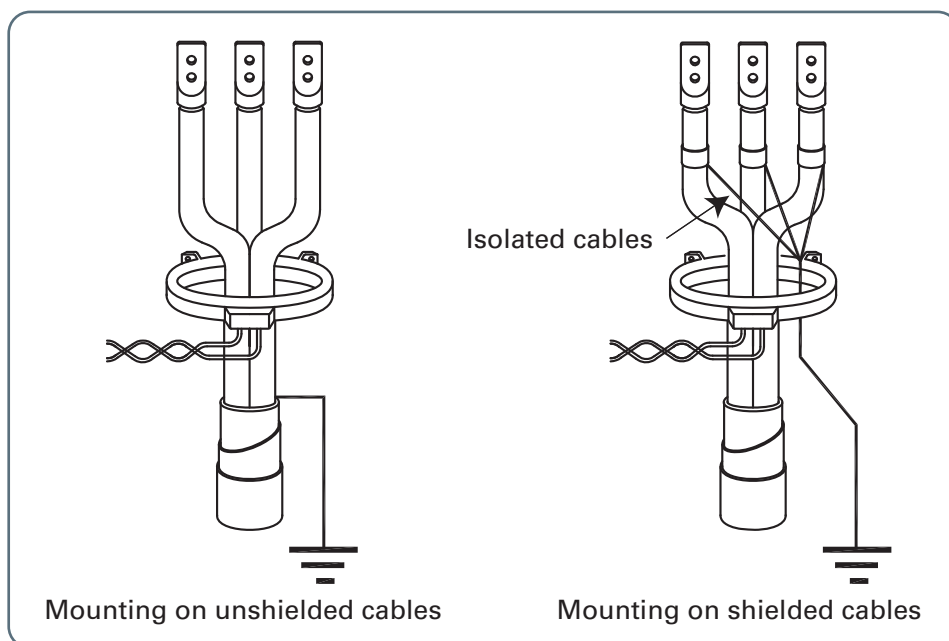
Residual current sensor

Note: for use on MV grid the installation on insulated cables is required!

Before fitting, make sure that there are no earth connections of the screens upstream of the sensor; in particular, for unified unipolar terminal ends, insulate support brackets from earth using the components supplied in the kit to the MT switchgear. Fig. 5, illustrating the assembly drawing of the entire compartment, shows the layout with plates, screws and insulating bolts. For different applications, refer to the MV panel manufacturer's instructions.

For a perfect sensor fitting, the three earth connection screens should be collected into a single bundle to be anchored to the central cable so as to implement an ordered fitting (fig.5); proceed as follows:

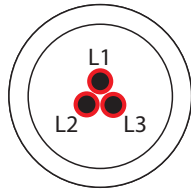
- split the two core parts removing the metal clamp fastening screw;
- fit the toroid so as to embrace the three cables, making sure that also the screening braiding earth connection is included;
- apply the metal clamp and tighten the fastening screw; align the two half cores properly so that references "P1" on the same cores are matching.
- The sensor fitting direction should be such as to have said references arranged towards the upper side of the MV compartment (line outgoing side downstream of switch).
- fasten the core using the insulating clamps supplied.



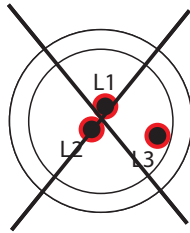
In order to ensure a linear response from the sensor, the cables must be positioned in the centre of the transformer so that the magnetic effect of the three cables is perfectly compensated in the absence of residual current (Correct installation).

Hence, the assembly indicated in the drawing (Improper installation), in which phase L3 causes local magnetic saturation whereby the vectorial sum of the three currents would be non-null, should be avoided.

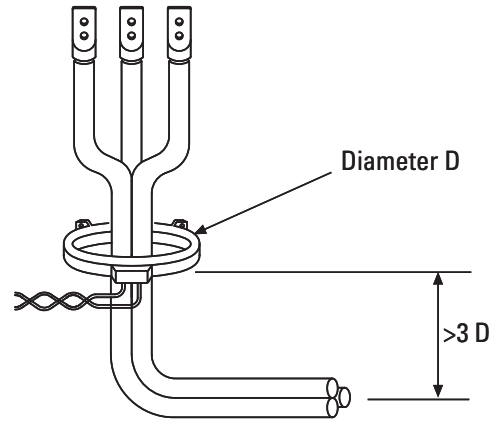
The same considerations also apply when the sensor is positioned near bends in the cabling. It is recommended that the transformer be placed away from bends in the conductors).



CORRECT INSTALLATION



IMPROPER INSTALLATION



Electrical connections

Electrical connections must comply with the connection diagram shown on the inside of the SME2 panel cover; they include:

- 1) connection to the current sensors;
- 2) connection to the remote control unit;
- 3) connection to the capacitive dividers;
- 4) connections to the earth terminal.

1) Fit the connection cables to the Ct's through the fair lead provided in the lower side of the case for a minimum length of 20 cm. Connect the cables to MA terminal board; the operations are made easier by the marks on the conductors and by the signatures print on the PCB.

2) As regards the connection to the remote control unit, the cable is supplied already abutted to the MB terminal board.

3) The connection cable to voltage sensors (capacitive dividers) is supplied already abutted to the MA terminal board, so you only have to connect the hexapolar plug to the relevant outlet (voltage on lights).

4) Connect the case to earth and implement the earth node between current sensor return conductors (CT).

Final operations

After wiring, make sure that no bare parts of the components come in contact with the circuit. As further precaution it is advisable to mechanically secure connection cables to the sensors, to capacitive dividers and to the remote control unit outside the SME2 panel, so as to prevent the cables from exerting any stress on the terminals.

6 COMMISSIONING

For start up, apply the auxiliary power voltage fitting the connector in the remote control outlet. Upon start up, all of the eight leds are controlled to light up for 1 s; afterwards, they turn off except for led V4, V8, V12, if voltage on the corresponding phases is ON.

In order to check the device operation, it is possible to measure the current input of the auxiliary power which, at rest conditions with voltage equal to the rated value of 24 V, must be within the 90 ... 130 mA range.

The settings must be made by Personal Computer with sw ThySetter

6.1 ThySetter

The ThySetter sw is a "browser" of data (setting, measure, etc.); it implements an engine that is afford to rebuild the menu set up and the relationships to data concerning all Thytronic protective relays by means of XML files.

Following operations are performed by means ThySetter:

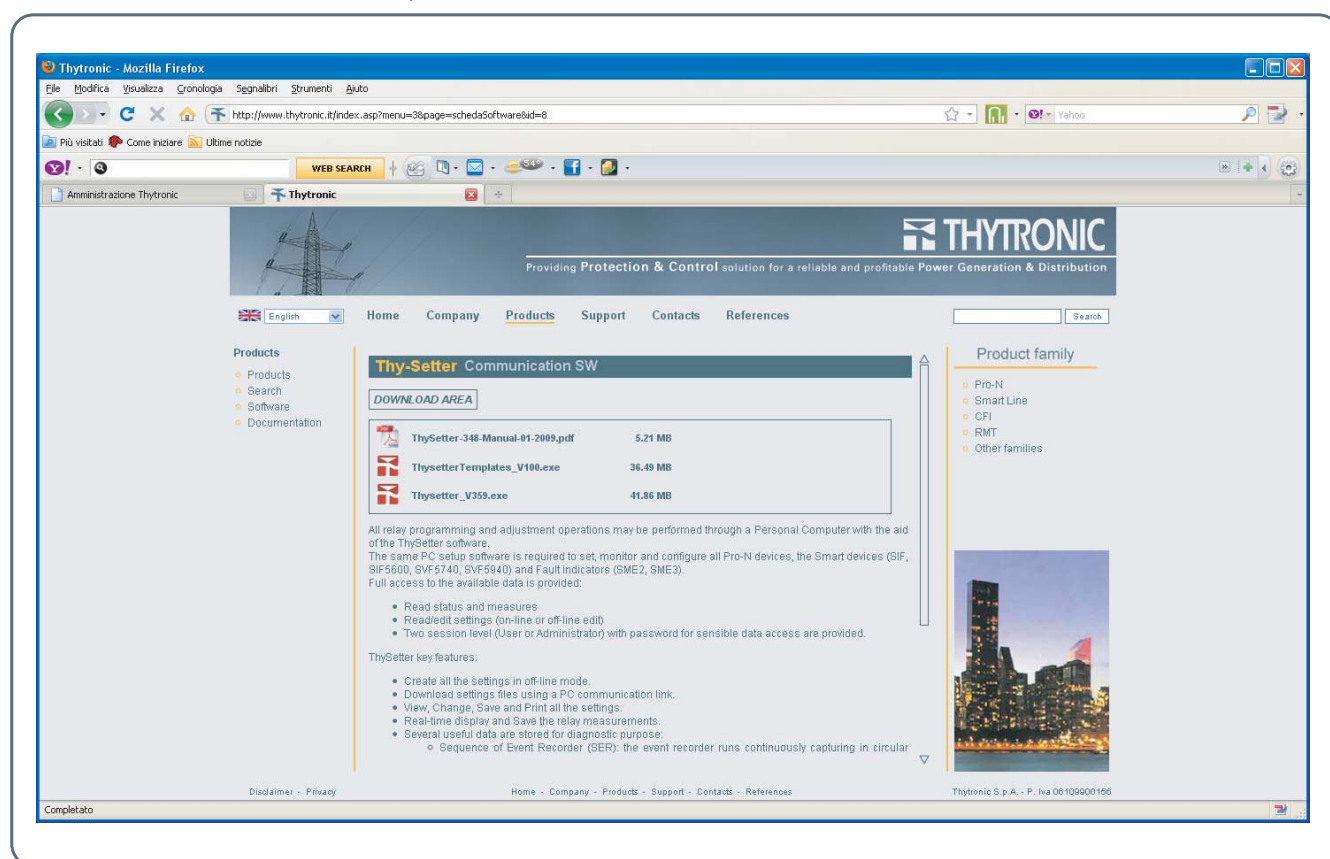
- Open-store of setting files;
- ASCII or Excel export reports;
- Open/close communication;
- Send settings, read settings;
- Firmware upgrades;
- Session level selection and log enabling (log files);

After the device selection Thysetter allows to:

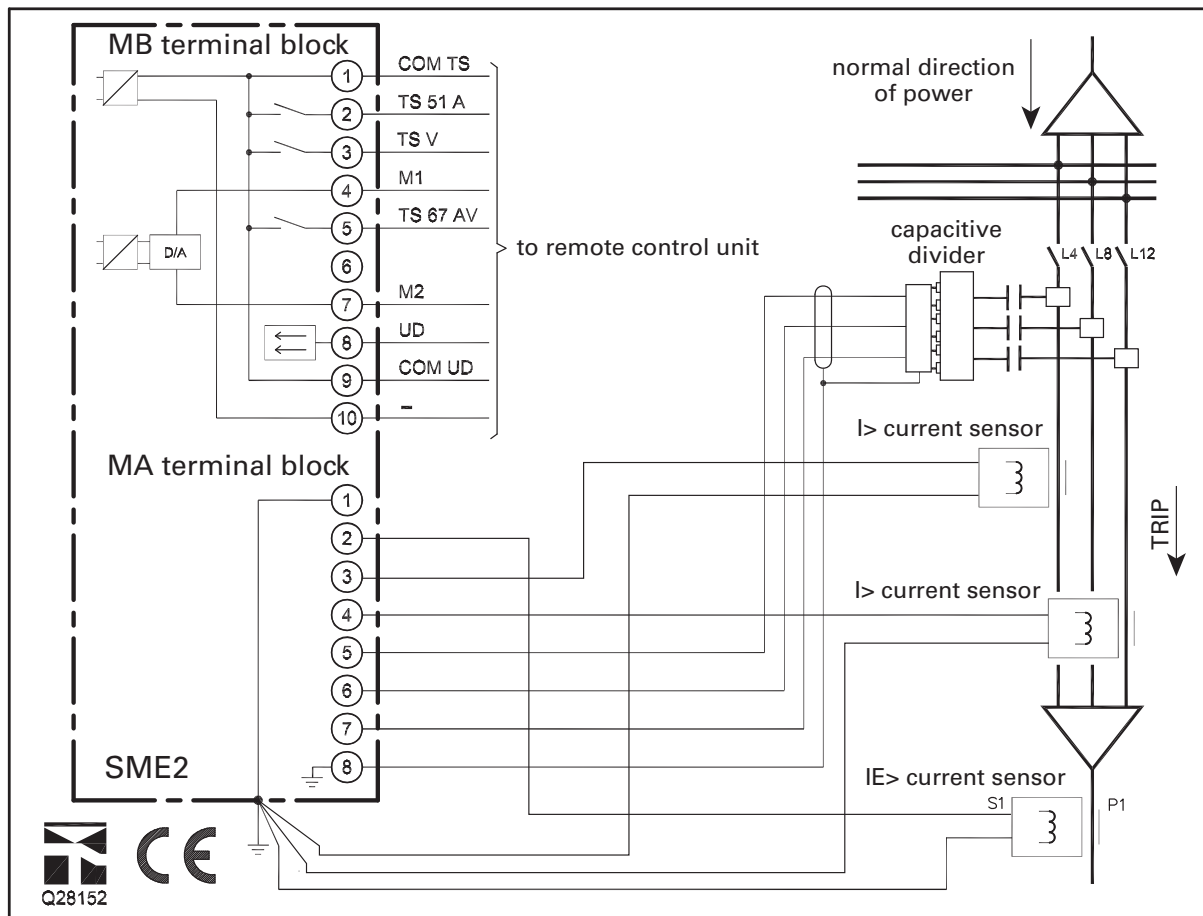
- Set the relay reference data;
 - Read info, measures, etc... ;
- Store settings.

ThySetter installation

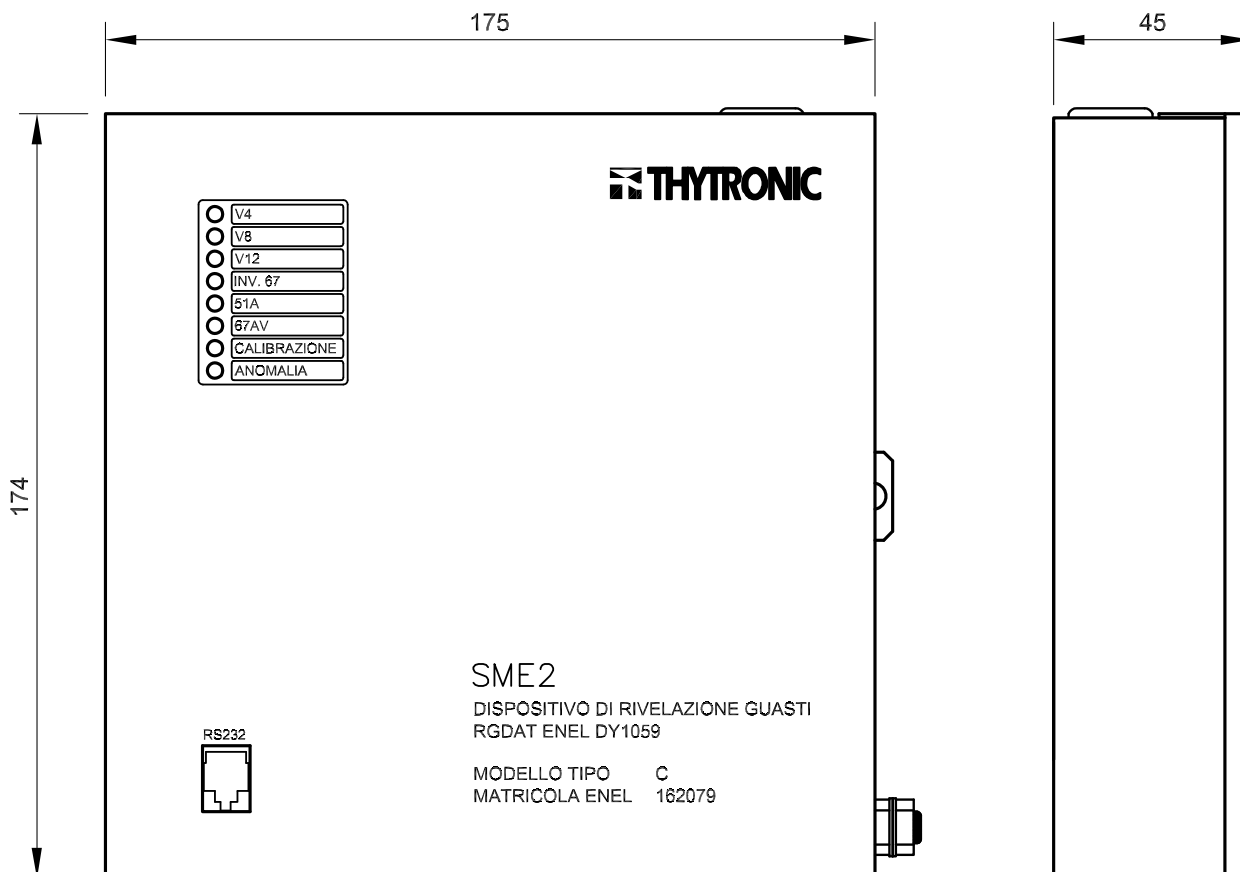
The ThySetter sw is available free of charge; the latest version can be downloaded from site www.thytronic.it (section PRODUCT/SOFTWARE APPLICATIONS/THY-SETTER/download area)



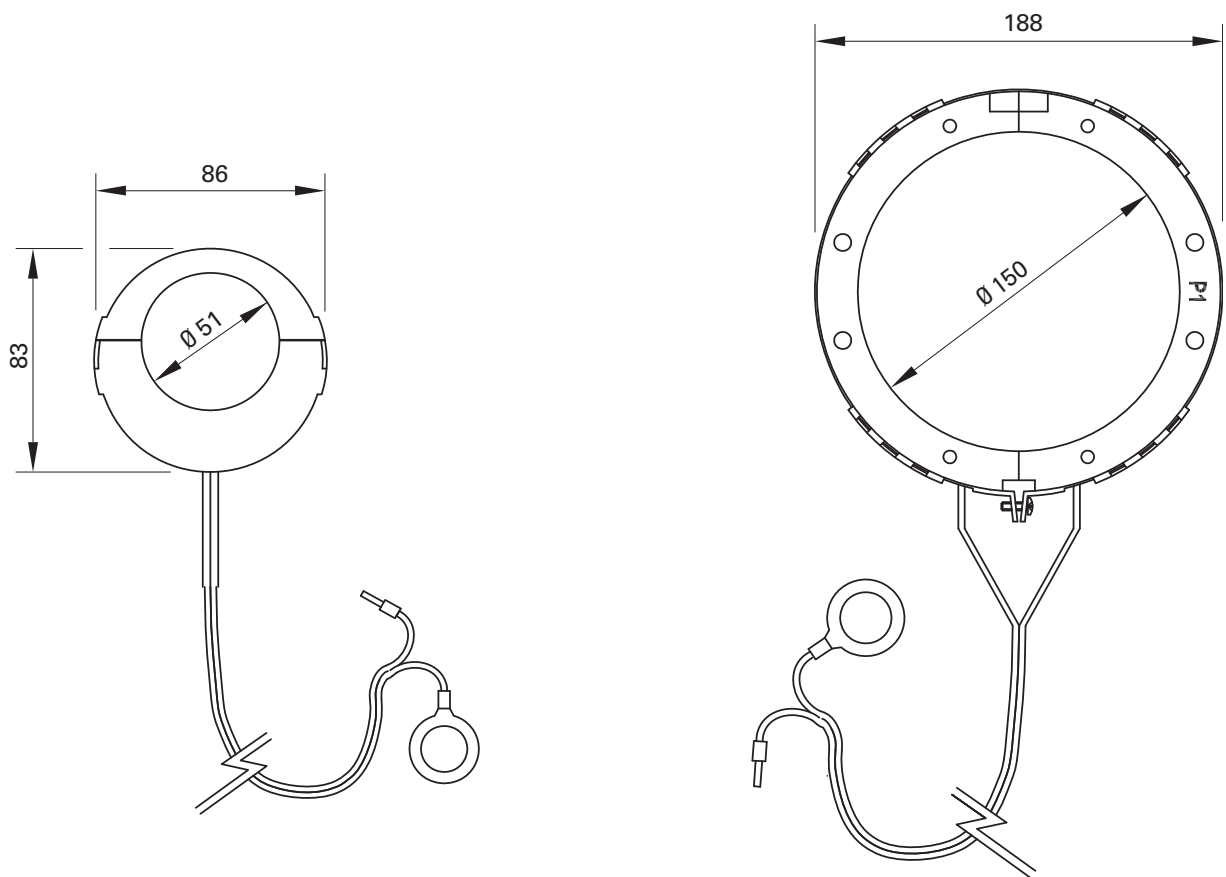
6.2 CONNECTION DIAGRAM



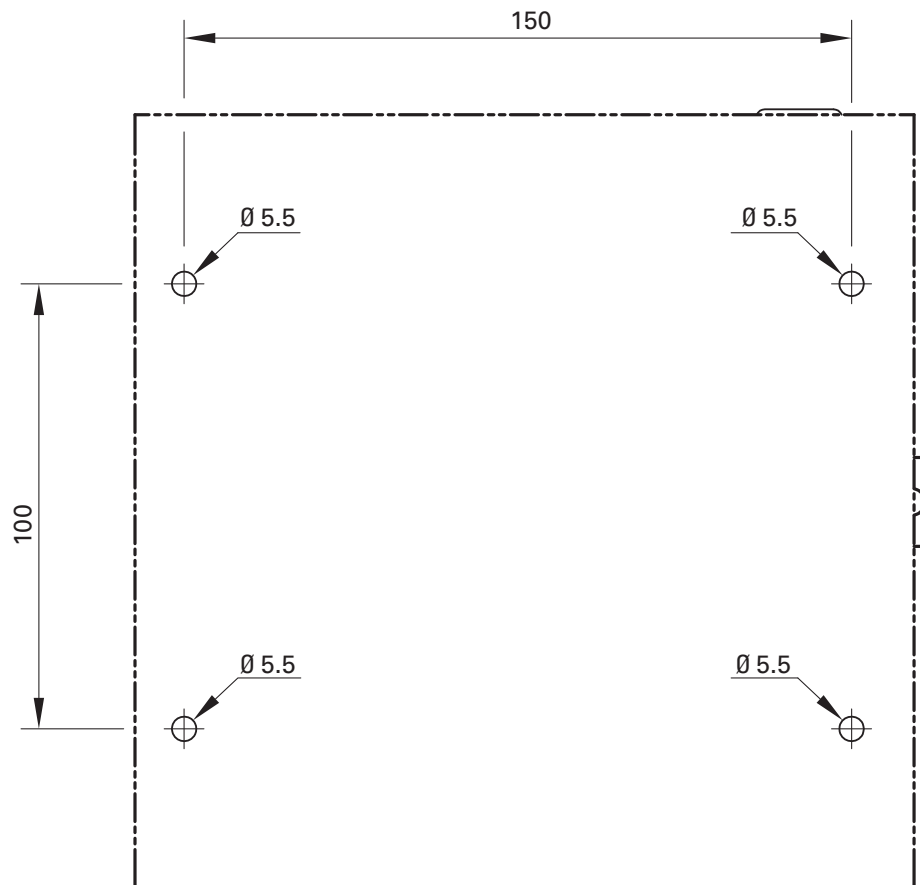
6.3 SME2 DEVICE



6.4 CURRENT SENSORS



6.5 CUTOUT



7 MAINTENANCE

The SME2 relays do not require any particular maintenance; all circuits use high quality static components, the subassembly products undergo dynamic checks on their functioning before the final assembling of the complete equipment. The dedicated circuits and the firmware for the self-test function continuously check the relay operation; the continuously operating auto-zeroing function dynamically corrects the measuring errors due to offset, heat dependent drifts, aging of components, etc.

The microprocessor is equipped with a watch-dog circuit which restores the correct operation of the firmware in case of fault.

8 STORAGE

The SME2 devices must be stored within the required temperature limits; the relative humidity should not cause condensation or formation of frost.

It is recommended that the devices are stored in their packaging; in the case of long storage, especially in extreme climatic conditions, it is recommended that the device is supplied with power for some hours before the commissioning, in order to bring the circuits to the rating conditions and to stabilize the operation of the components.